

System-Level Programming

29 Signals

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- A microcontroller can react to concurrent events (interrupts) with so-called interrupt service routines.
- A similar concept exists on the level of processes: **signals**



Interrupt: asynchronous signal triggered by an “external” event

- CTRL-C was pressed on the keyboard
- timer expired
- child process terminated
- ...

Exception: synchronous signal triggered by an activity of a process

- access to invalid memory addresses
- illegal machine instruction
- division by 0
- writing to a closed communication connection
- ...

Communication: a process sends an event to another process



Signals (3)

CTRL-C:

```
int main(void)
{
    while (1) {
    }
}
```

```
~> ./test
^C
~>
```

Illegal memory access:

```
int main(void)
{
    *(int *) NULL = 0;
    return 0;
}
```

```
~> ./test
Segmentation fault
~>
```

Inter-process communication:

```
int main(void)
{
    while (1) {
    }
}
```

```
~> ./test
Terminated
~>
```

```
~> killall test
~>
```



abort:

creates a core dump (contents from memory and registers are saved in the file `./core`) and terminates the process
default setting for all exceptions (to make debugging easier)

exit:

terminates the process (without core dump)
default setting for e. g., CTRL-C, kill signal

ignore:

signal gets ignored
default setting for all “unimportant” signals (e. g., child process terminated, size of the terminal window has changed)

...



Reaction to Signals (2)

...

handler:

call to a signal handler function, continuation afterwards
no default setting possible since it is dependent on the program

stop:

stops the process
default setting for stop signal

continue:

continues a process
default setting for continue signal

Reaction can be changed with system call (**sigaction**).



- Configuration of the signal handler function
(equivalent to configuring a function as ISR)

```
#include <signal.h>

int sigaction(int sig, struct sigaction *new, struct sigaction *old);
```

struct sigaction contains:

```
void (*sa_handler)(int sig); /* handler function
                                or SIG_DFL or SIG_IGN */
sigset_t sa_mask;           /* list of blocked signals while
                                handler is executed */
int sa_flags;               /* 0 or SA_RESTART ... */
```

■ ...



- ...
- Blocking/unblocking of signals
(equivalent to `cli()`, `sei()`)

```
#include <signal.h>

int sigprocmask(int how, sigset_t *nmask, sigset_t *omask);
```

- `SIG_BLOCK`: block all given signals
- `SIG_UNBLOCK`: unblock all given signals
- `SIG_SETMASK`: set a signal mask

- Unblock + passive waiting for signal + blocking again
(equivalent to `sei()`; `sleep_cpu()`; `cli()`)

```
#include <signal.h>

int sigsuspend(sigset_t *mask);
```

...



Programming Interface

- ...
- Creating an empty signal list

```
#include <signal.h>  
  
int sigemptyset(sigset_t *mask);
```

- Creating a full signal list

```
int sigfillset(sigset_t *mask);
```

- Adding one signal to an existing signal list

```
int sigaddset(sigset_t *mask, int sig);
```

- Removing one signal from an existing signal list

```
int sigdelset(sigset_t *mask, int sig);
```



- Typical signals:
 - SIGSEGV**: “Segmentation Fault” (invalid access to memory)
 - SIGINT**: “Interrupt” (CTRL-C)
 - SIGALRM**: “Alarm” (timer expired)
 - SIGCHLD**: “Child” (child process terminated)
 - SIGTERM**: “Terminate” (termination of the process; possible to handle in program)
 - SIGKILL**: “Kill” (termination of the process; impossible to handle in program)



Signal Example 1

```
#include <signal.h>
#include <stdio.h>
#include <string.h>
#include <unistd.h>

int main(void)
{
    // Call handler when
    // CTRL-C signal is received.
    struct sigaction sa;
    sa.sa_handler = handler;
    sigfillset(&sa.sa_mask);
    sa.sa_flags = 0;
    sigaction(SIGINT, &sa, NULL);

    for (int i = 0; ; i++) {
        printf("%d\n", i);
    }
    return 0;
}
```

```
static void handler(int sig)
{
    char s[] = "CTRL-C!\n";
    write(STDOUT_FILENO,
          s, strlen(s));
}
```

(error handling omitted...)

```
~> ./test
...
146431
146432
146433
14^CCTRL-C!
6434
146435
146436
...
~>
```



Signal Example 2

```
int main(void)
{
    // Call handler when
    // timer signal is received.
    struct sigaction sa;
    sa.sa_handler = handler;
    sigfillset(&sa.sa_mask);
    sa.sa_flags = 0;
    sigaction(SIGALRM, &sa, NULL);

    // Send timer signal every sec.
    struct itimerval it;
    it.it_value.tv_sec = 1;
    it.it_value.tv_usec = 0;
    it.it_interval.tv_sec = 1;
    it.it_interval.tv_usec = 0;
    setitimer(ITIMER_REAL, &it, NULL);

    // Wait for timer ticks.
    sigset(SIGPOLLIN, mask);
    sigemptyset(&mask);
    while (1) sigsuspend(&mask);
}
```

```
static void handler(int sig)
{
    write(STDOUT_FILENO,
          "Tick\n", 5);
}
```

(error handling omitted...)

```
~> ./test
Tick
Tick
Tick
^C
~>
```



Signal Example 3

```
#include <signal.h>
#include <unistd.h>

int main(void)
{
    // Call handler when
    // I/O signal is received.
    struct sigaction sa;
    sa.sa_handler = handler;
    sigfillset(&sa.sa_mask);
    sa.sa_flags = 0;
    sigaction(SIGIO, &sa, NULL);

    // Send I/O signal when
    // STDIN can be read.
    int flags = fcntl(STDIN_FILENO,
                      F_GETFL);
    flags |= O_ASYNC;
    fcntl(STDIN_FILENO, F_SETFL,
          flags);

    while (1) sleep(1);
}
```

```
static void handler(int sig)
{
    char buf[256];
    int len;

    // Read chars from STDIN.
    len = read(STDIN_FILENO, buf,
               sizeof(buf));

    // Handle chars in buf.
    ...
}
```

(error handling omitted...)



- Signals create **concurrency** inside processes
- Resulting problems are analogous to concurrency of interrupts on a microcontroller platform
- For example: lost update, lost wakeup, ...



Example of Concurrency

```
int main(void) {
    struct sigaction sa;
    struct itimerval it;
    /* Setup timer tick handler. */
    sa.sa_handler = tick;
    sa.sa_flags = 0;
    sigfillset(&sa.sa_mask);
    sigaction(SIGALRM, &sa, NULL);
    /* Setup timer. */
    it.it_value.tv_sec = 1;
    it.it_value.tv_usec = 0;
    it.it_interval.tv_sec = 1;
    it.it_interval.tv_usec = 0;
    setitimer(ITIMER_REAL, &it, NULL);
    /* Print time while working. */
    while (1) {           ↓ signal here
        int s = sec, m = min, h = hour;
        printf("%02d:%02d:%02d\n", h, m, s);
        do_work();
    }
}
```

(error handling omitted...)

```
volatile int hour = 0;
volatile int min = 0;
volatile int sec = 0;

static void tick(int sig) {
    sec++;
    if (60 <= sec) {
        sec = 0; min++;
    }
    if (60 <= min) {
        min = 0; hour++;
    }
    if (24 <= hour) {
        hour = 0;
    }
}
```

~> ./test

...

23:59:59

00:59:59

00:00:00

...

← problem here!

Solution for the Concurrency Example

1. Solution

```
sigset_t nmask, omask;

/* Block SIGALRM. */
sigemptyset(&nmask);
sigaddset(&nmask, SIGALRM);
sigprocmask(SIG_BLOCK,
            &nmask, &omask);

/* Get current time. */
int s = sec, m = min, h = hour;

/* Restore signal mask. */
sigprocmask(SIG_SETMASK,
            &omask, NULL);

/* Print current time. */
printf("%02d:%02d:%02d\n",
      h, m, s);
```

2. Solution

```
/* Get current time. */
int s, m, h;
do {
    s = sec;
    m = min;
    h = hour;
} while (s != sec
         || m != min
         || h != hour);

/* Print current time. */
printf("%02d:%02d:%02d\n",
      h, m, s);
```

More solutions exist...



Problems with Concurrency

- Additional problem:
internal functionality of library functions unknown in general
- Example 1:
`printf` inserts character into a buffer
⇒ use of `printf` in the main program *and* in the signal handler is dangerous
- Example 2:
`malloc` searches list for free memory area; `free` inserts a block into the list
⇒ use of `malloc/free` in the main program *and* in the signal handler is dangerous
- Solution:
 - signals should be blocked during the execution of **critical sections** or
 - no unknown library functions should be called from inside a signal handler function

