

Exercises in System Level Programming (SLP) – Summer Term 2024

Exercise 8

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Chair in Distributed Systems
and Operating Systems



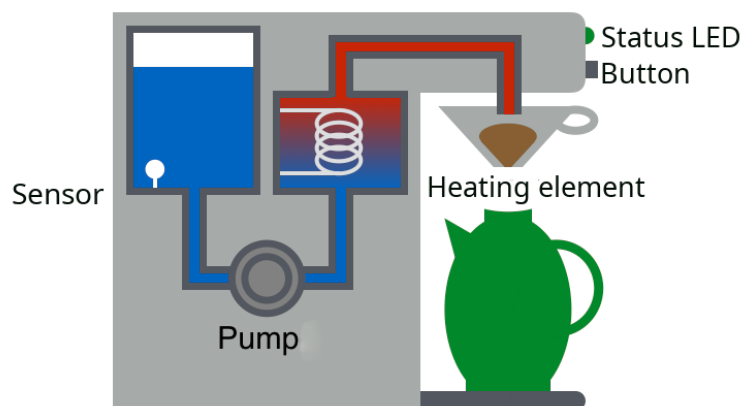
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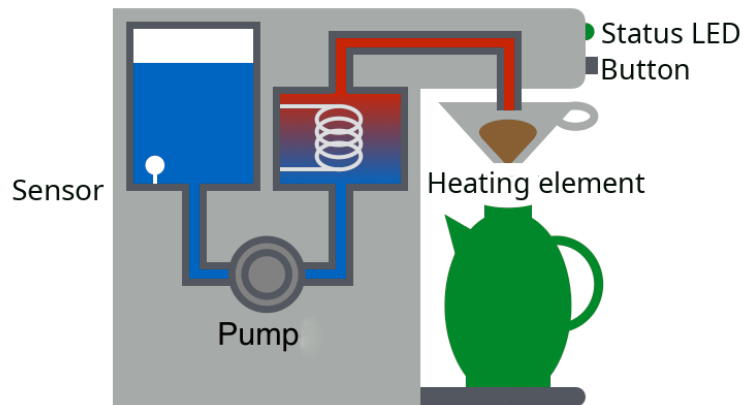
Presentation Assignment 4

Hands-on: Coffee Machine

Hands-on: Coffee Machine (1)



- Learning goals:
 - Finite state machines
 - Timers and alarms
 - Interrupts & sleep modes



■ Wiring:

- Pump & heating: Port D, Pin 5 (active-low)
- Button: INT0 an Port D, Pin 2 (active-low)
- Sensor: INT1 an Port D, Pin 3 (water: high; no water: low)
- State LED:
 - BLUE0: **STANDBY**
 - GREEN0: **ACTIVE**
 - RED0: **NO_WATER**

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STANDBY

- Machine is switched off
- Pump and heating are off
- User can start making coffee by pressing the button
- Initial state

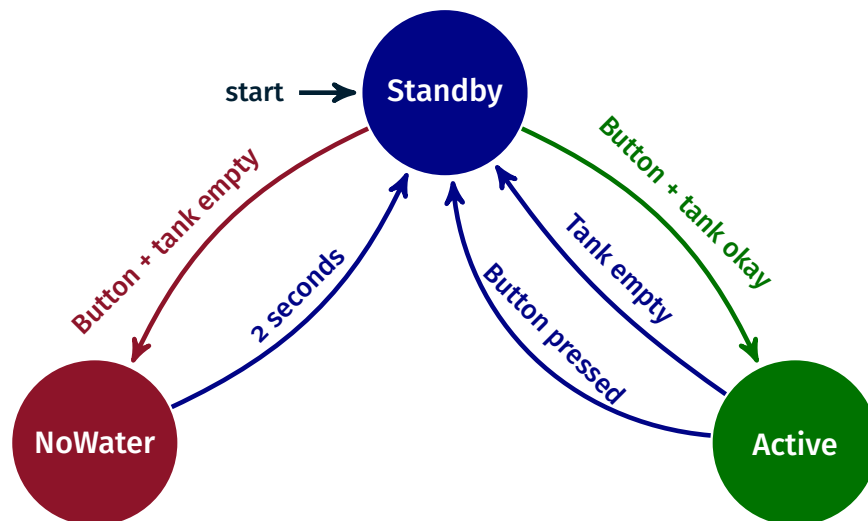
ACTIVE

- Machine is switched on
- Pump and heating are on
- Water tank is not empty
- User can stop the machine by pressing the button

NO_WATER

- Coffee machine shows that not enough water is in the tank
- Pump and heating are off
- Time period: 2 seconds

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■ Hints:

- Pressed button & change of water level by interrupts
- State LED: `void setLEDState(state_t state)`
- Waiting phases can be implemented using the single-shot alarms
- During waiting phases always enter a power-saving mode

4



DDRx Configuration of pin i of port x as in-/output

- Bit $i = 1 \rightarrow$ Pin i as output
- Bit $i = 0 \rightarrow$ Pin i as input

PORTx Mode of operation **depends on DDRx**:

- If pin i is **configured as output**, then bit i in the PORTx register controls whether a high level or a low level has to be generated at pin i
 - Bit $i = 1 \rightarrow$ high level at pin i
 - Bit $i = 0 \rightarrow$ low level a pin i
- If pin i is **configured as input**, then the internal pull-up resistor can be activated
 - Bit $i = 1 \rightarrow$ pull-up resistor at pin i (level is pulled high)
 - Bit $i = 0 \rightarrow$ pin i configured as tri-state

PINx Bit i returns the current level of pin i at port x (read only)

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- Interrupt sense control (ISC) bits of the ATmega328PB are located at the external interrupt control register A (EICRA)
- Position of the ISC-bits inside the register defined by macros

Interrupt INT0		Interrupt on	Interrupt INT1	
ISC01	ISC00		ISC11	ISC10
0	0	low level	0	0
0	1	either edge	0	1
1	0	falling edge	1	0
1	1	rising edge	1	1

- ATmega328PB: External interrupt mask register (EIMSK)
- The position of the bits in this register is also defined by macros INTn

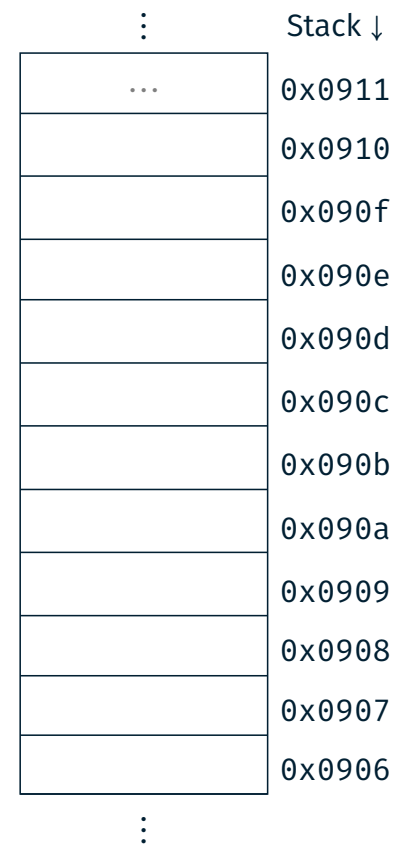
Hands-on: Ticker



- char: Single character (e.g. 'a')
- String: Array of chars (e.g. "Hello")
- C: Last char of a string: '\0'
 ⇒ Memory requirement: strlen(s) + 1

```

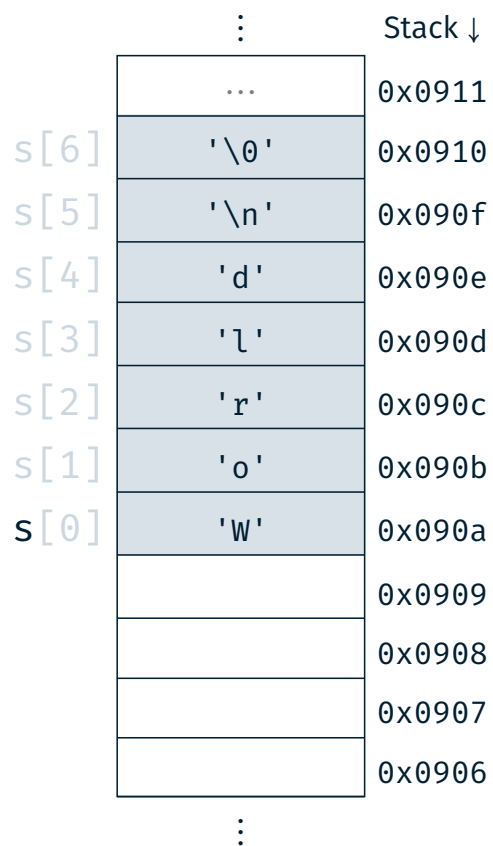
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04 char *s2 = s + 2;
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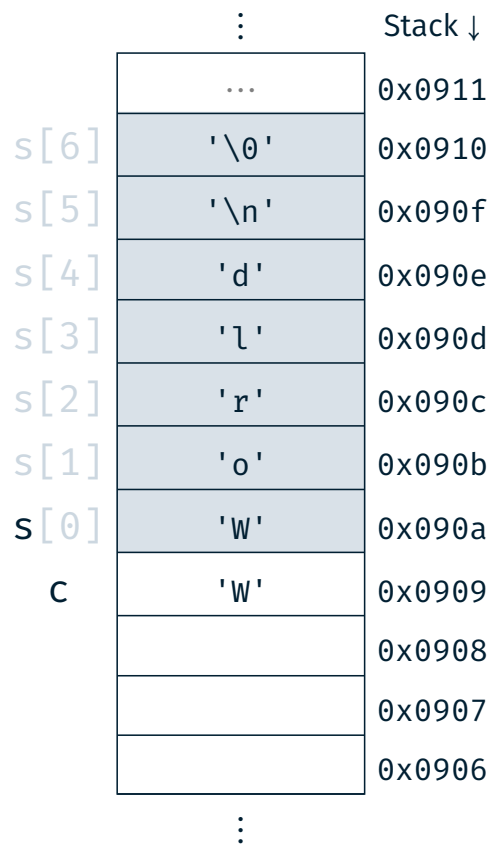




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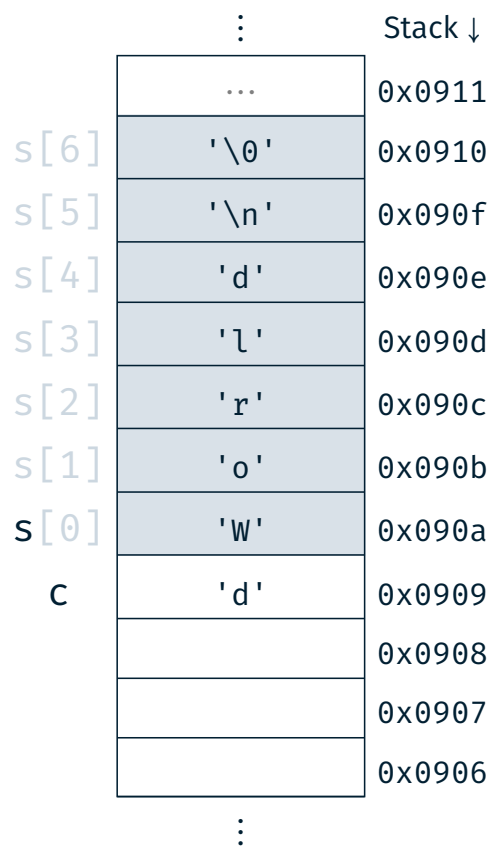
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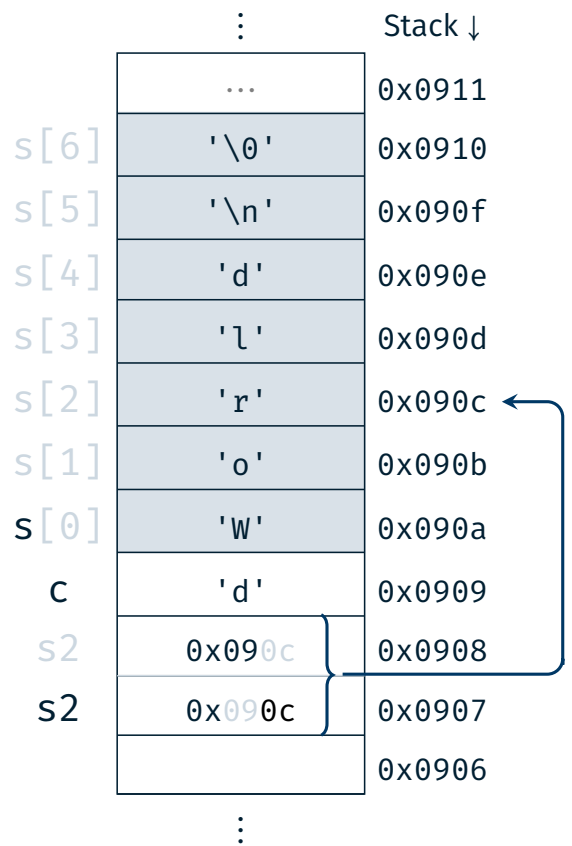




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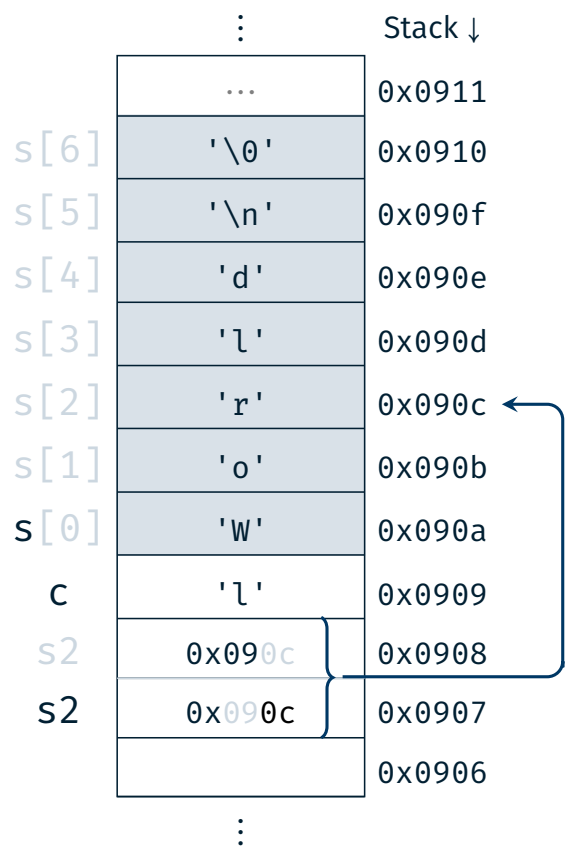
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- **Functionality:**
 - Displaying a text step-by-step on the 7-segment display
- **Learning goals:**
 - Strings in C
 - Pointers & pointer arithmetic
 - Alarms & sleep modes
- **Procedure:**
 - Recurring alarms with TIMER0
 - Combining the current substring
 - Output via the 7-segment display
 - During waiting phases, the microcontroller has to enter a sleep mode (passive waiting)

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Hands-on: Ticker – Determine Substrings



```
01 const char *string = "HELLO SPIC";
02 const char *current = string;
03 // current[0] == 'H' && current[1] == 'E'
04 ++current;
05 // current[0] == 'E' && current[1] == 'L'
06 // [...]
07 // current[0] == '\0', current[1] == ??
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12



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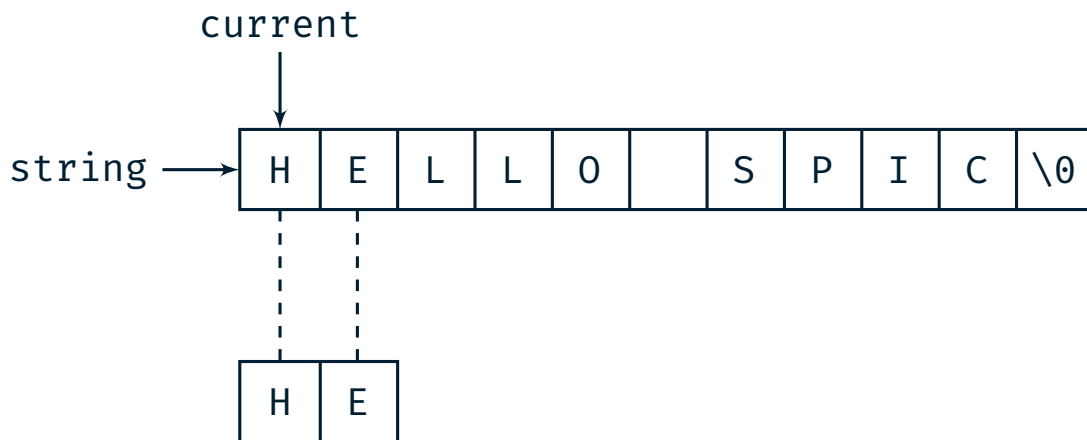
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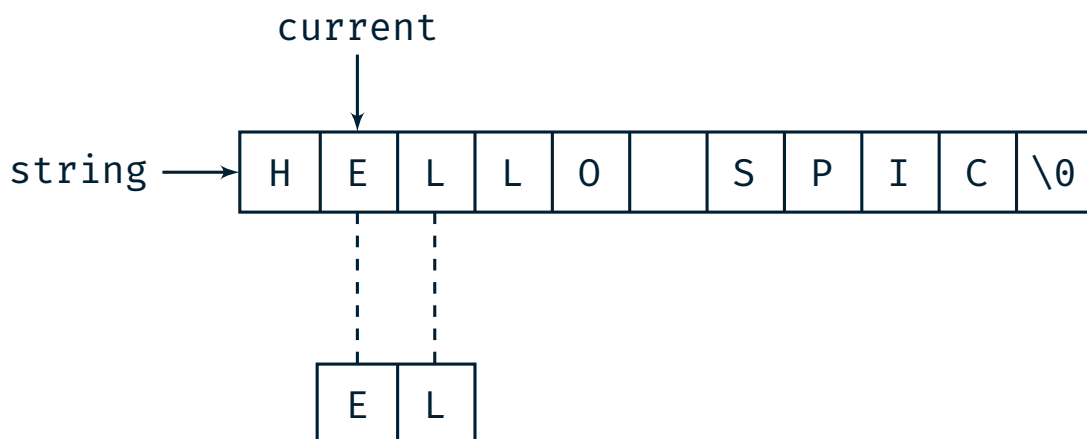
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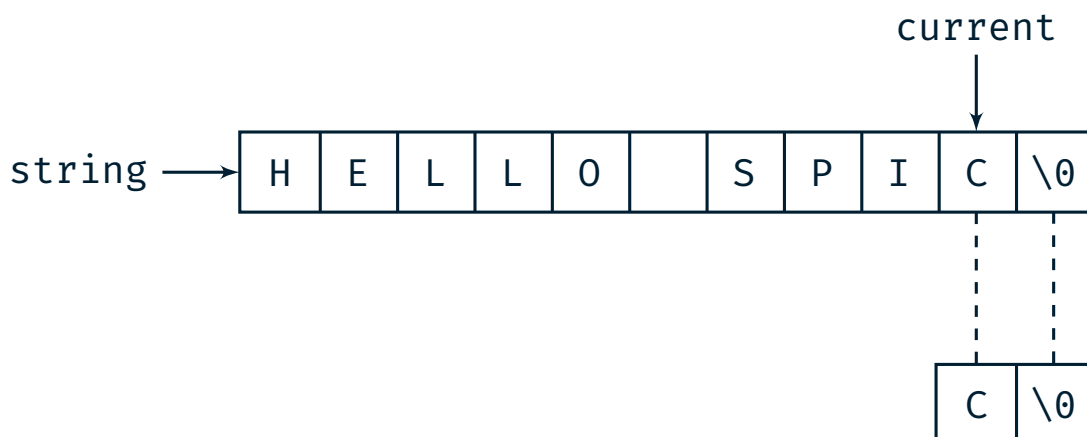
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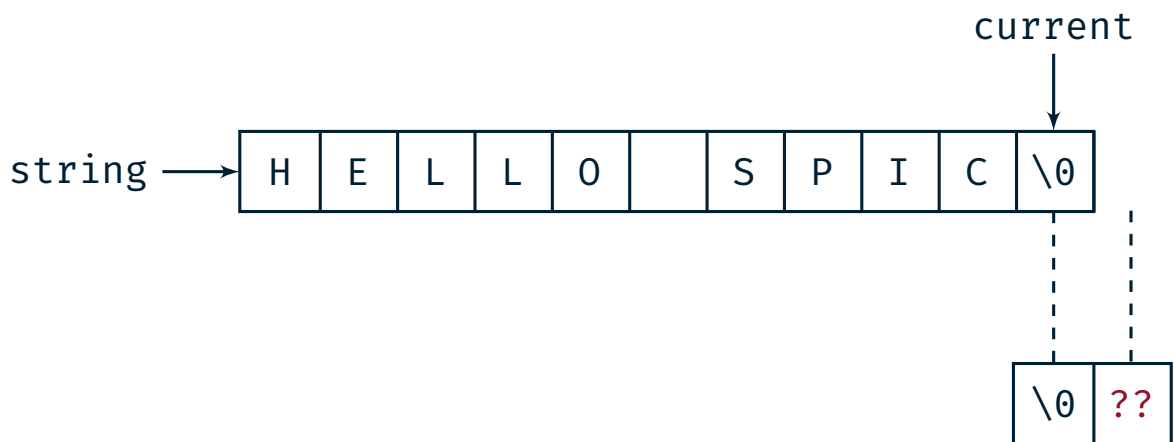


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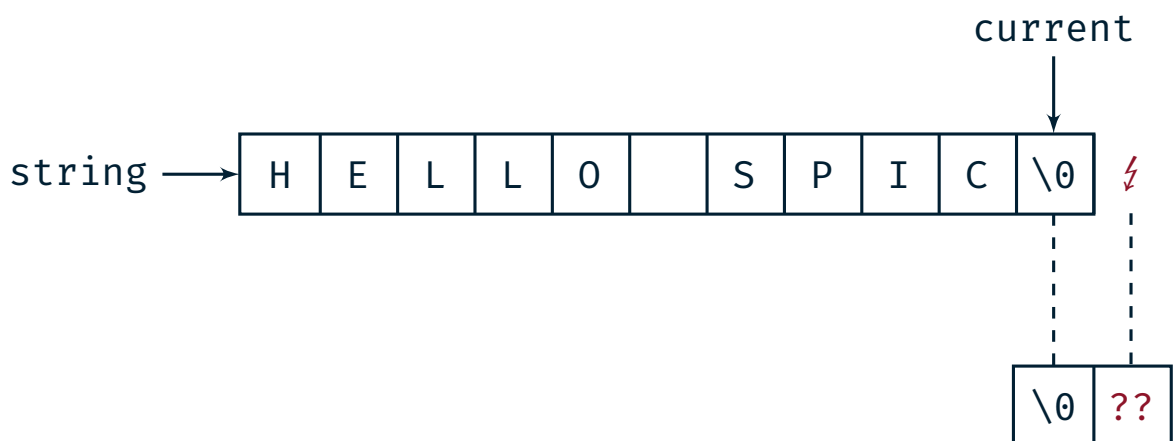
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