

Verlässliche Echtzeitsysteme

Übungen zur Vorlesung

Dynamische Stackbedarfsanalyse

Phillip Raffeck, Tim Rheinfels, Simon Schuster, Peter Wägemann

Friedrich-Alexander-Universität Erlangen-Nürnberg
Lehrstuhl Informatik 4 (Verteilte Systeme und Betriebssysteme)
<https://sys.cs.fau.de>

Wintersemester 2022



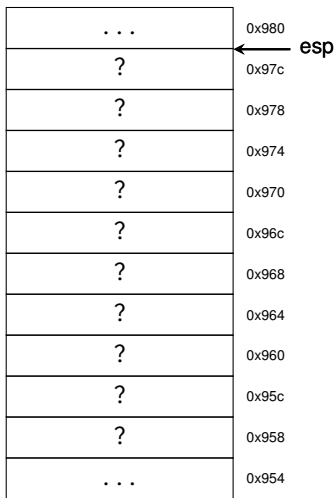


- **Harte, verlässliche Echtzeitsysteme**
 - Garantien über Ressourcenbedarf notwendig
 - ☞ statische Analyse unabdingbar
- **Mögliche Ressourcen: Speicherbedarf, Laufzeit, etc.**
- **Übung: Analyse des Stackbedarfs einer Bibliothek**
- **Stack-Analyse**
 1. Dynamisch: Wasserstandstechnik
 2. Statisch: „Eigenbau“ und aiT (Stack-Analyzer der a³ Suite)

Beispiel: Programmstapel

```
int main(void) {  
→ return f(4, 2);  
}
```

```
52a: push ebp  
52b: mov ebp, esp  
52d: lea ...  
534: or ...  
538: lea ...  
→ 53f: push 0x2  
541: push 0x4  
543: call 4fd <f>  
548: add esp, 0x8  
54b: leave  
54c: ret
```

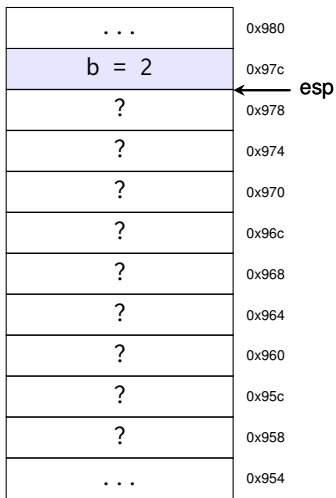


Wachstumsrichtung

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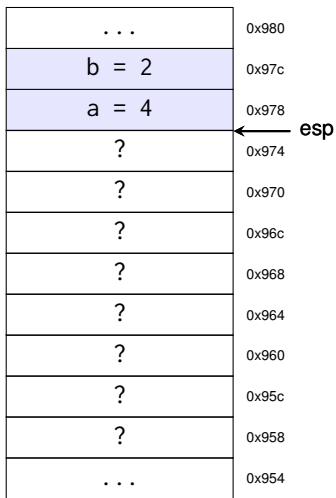
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52a:  push ebp  
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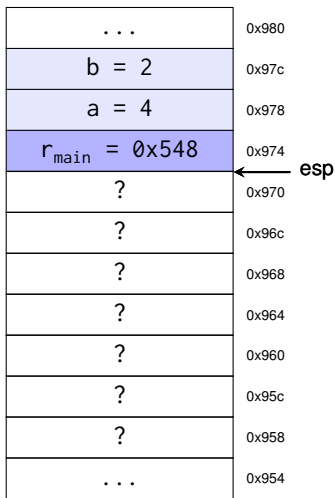
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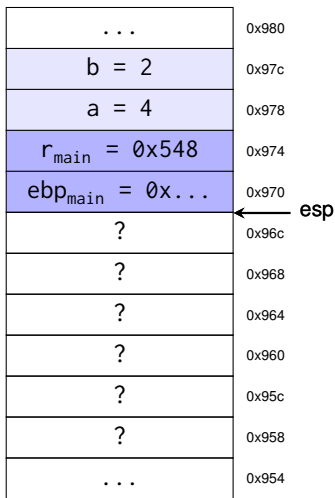
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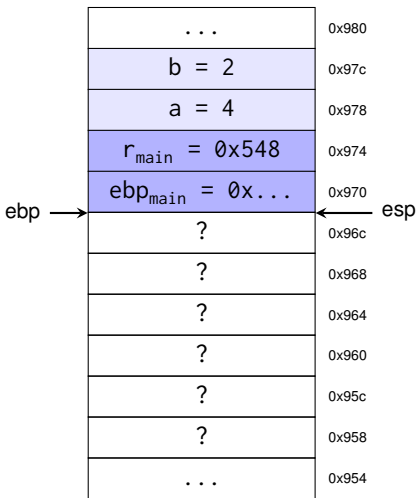
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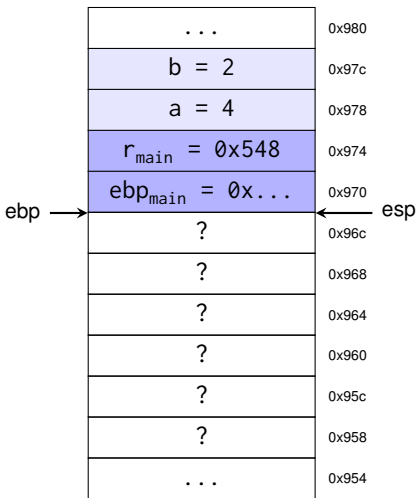
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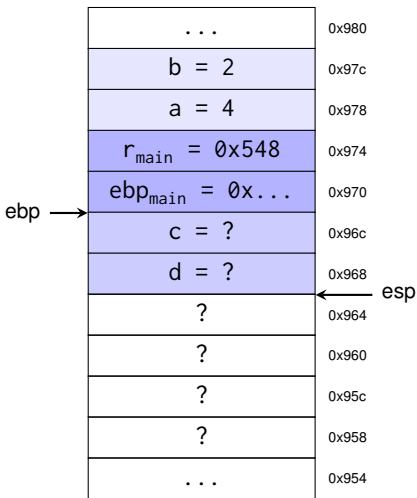
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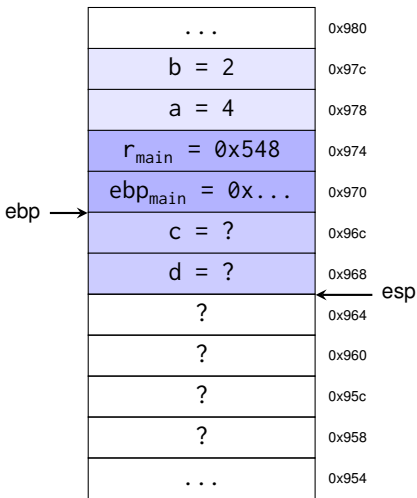
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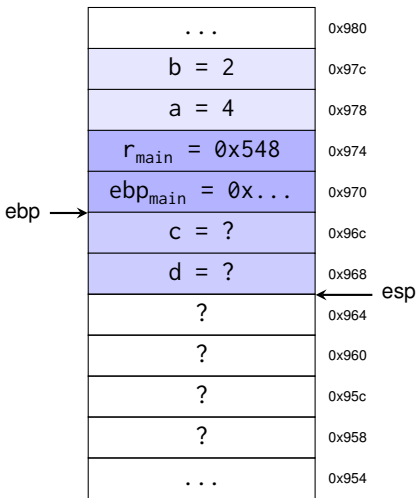
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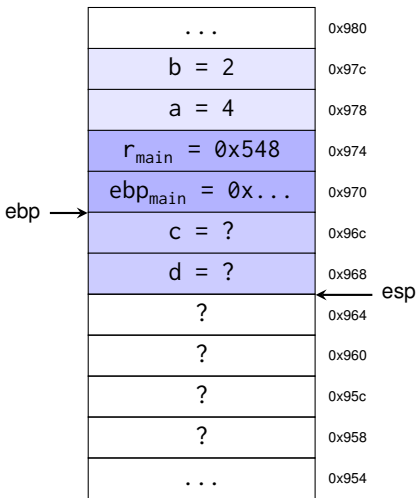
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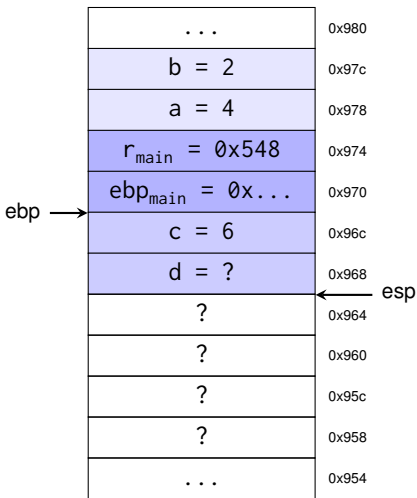


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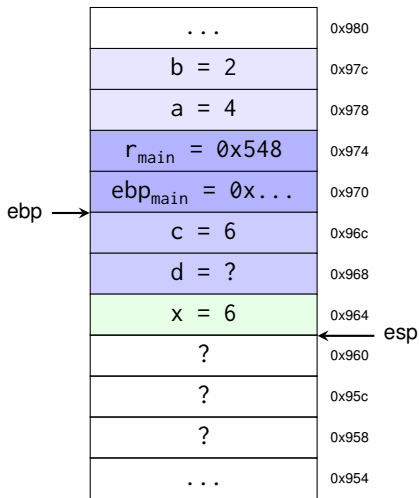
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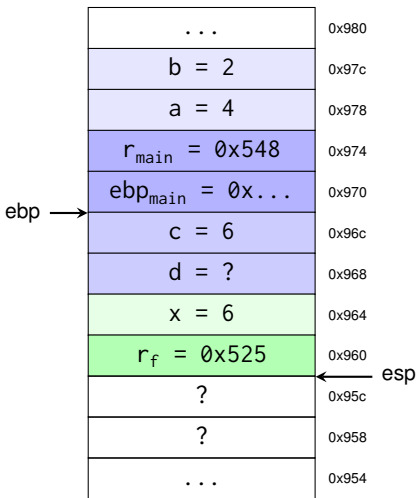
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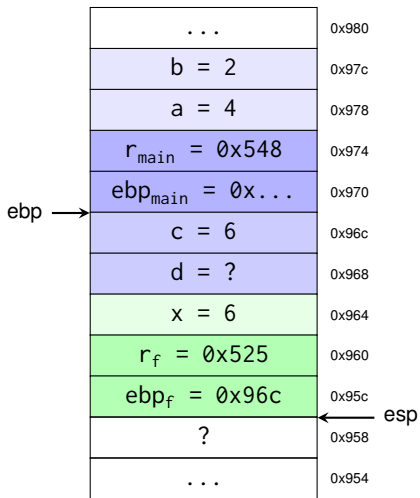
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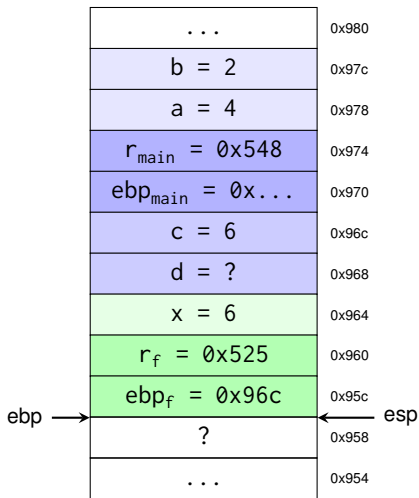
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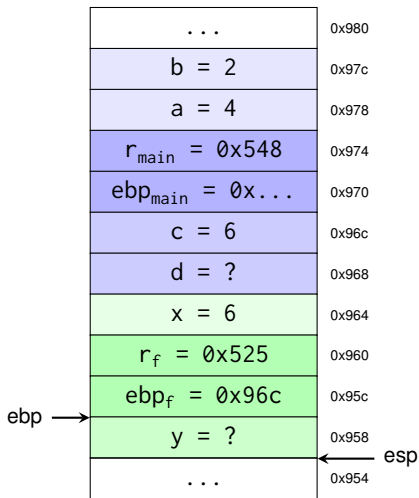
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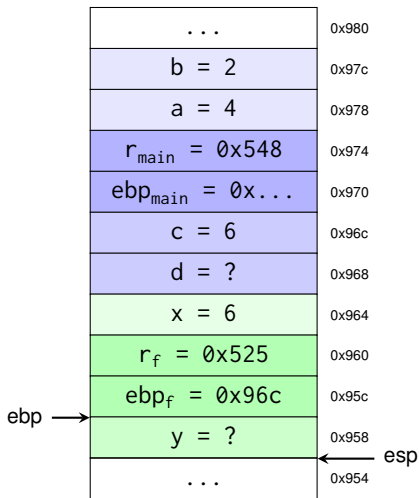
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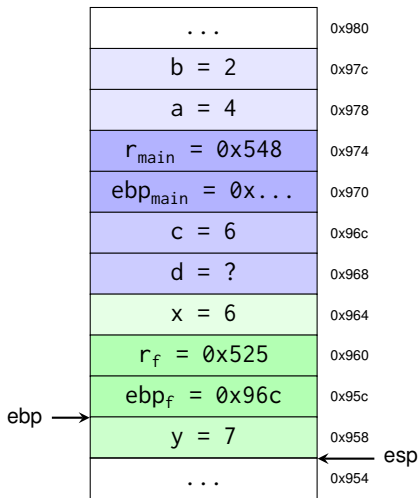
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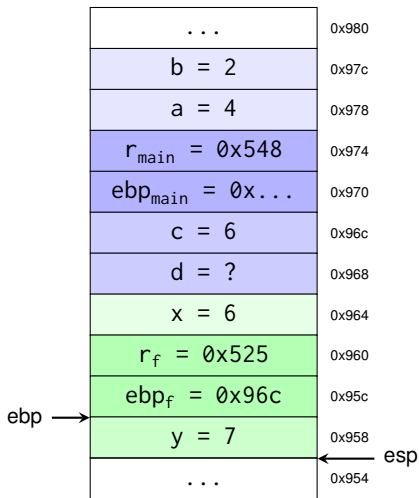
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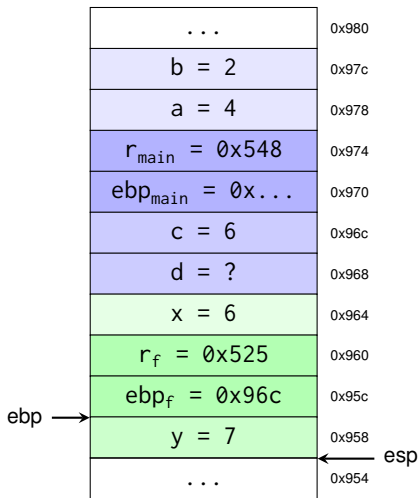
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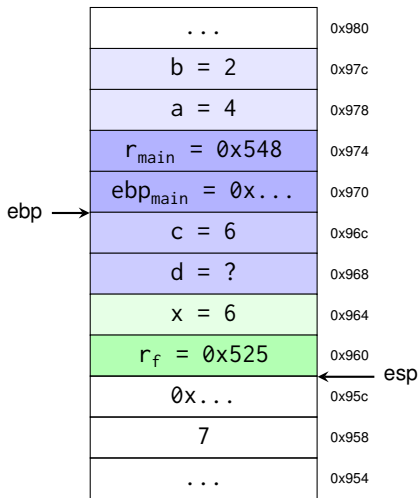
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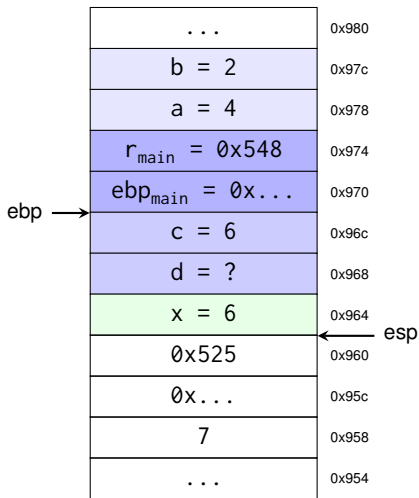
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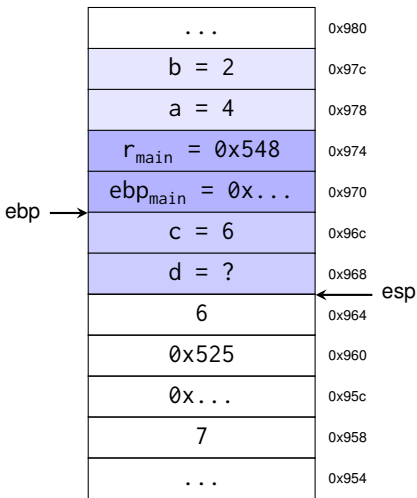
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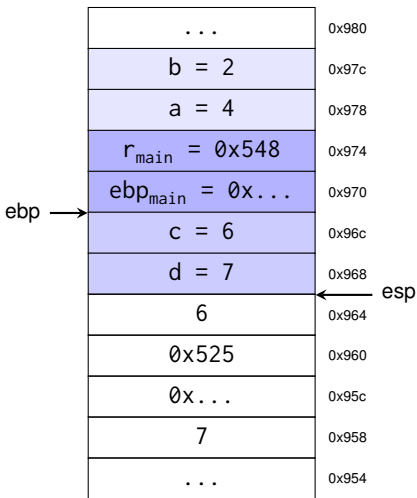
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520:  call 4e9 <g>  
525:  add  esp,0x4  
528:  mov  DWORD PTR [ebp-0x4],eax  
52b:  mov  eax,DWORD PTR [ebp-0x4]  
52e:  leave  
52f:  ret
```



Beispiel: Programmstapel

```
int f(int a, int b) {  
    int c = a + b;  
    int d = g(c);  
    return d;  
}
```

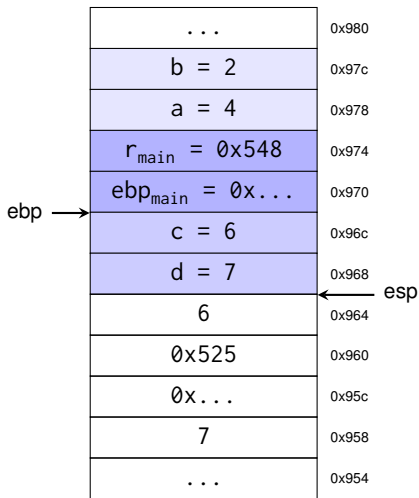
```
4fd:  push ebp  
4fe:  mov  ebp,esp  
500:  lea  ...  
507:  or   ...  
50b:  sub  esp,0x8  
512:  mov  edx,DWORD PTR [ebp+0x8]  
515:  mov  eax,DWORD PTR [ebp+0xc]  
518:  add  eax,edx  
51a:  mov  DWORD PTR [ebp-0x8],eax  
51d:  push DWORD PTR [ebp-0x8]  
520:  call 4e9 <g>  
525:  add  esp,0x4  
528:  mov  DWORD PTR [ebp-0x4],eax  
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Beispiel: Programmstapel

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    int c = a + b;  
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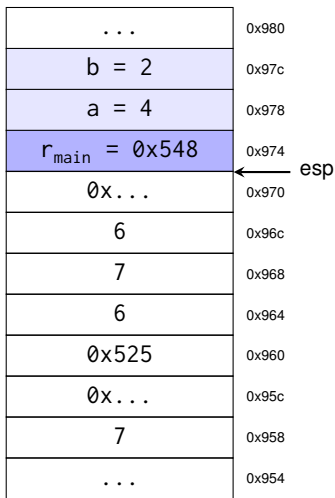
```
4fd:  push ebp  
4fe:  mov  ebp,esp  
500:  lea  ...  
507:  or   ...  
50b:  sub  esp,0x8  
512:  mov  edx,DWORD PTR [ebp+0x8]  
515:  mov  eax,DWORD PTR [ebp+0xc]  
518:  add  eax,edx  
51a:  mov  DWORD PTR [ebp-0x8],eax  
51d:  push DWORD PTR [ebp-0x8]  
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525:  add  esp,0x4  
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```



Beispiel: Programmstapel

```
int f(int a, int b) {  
    int c = a + b;  
    int d = g(c);  
    return d;  
}
```

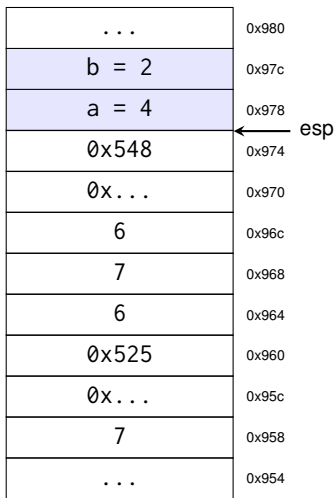
```
4fd:  push ebp  
4fe:  mov  ebp,esp  
500:  lea  ...  
507:  or   ...  
50b:  sub  esp,0x8  
512:  mov  edx,DWORD PTR [ebp+0x8]  
515:  mov  eax,DWORD PTR [ebp+0xc]  
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52e:  leave  
52f:  ret
```



Beispiel: Programmstapel

```
→ int main(void) {  
    return f(4, 2);  
}
```

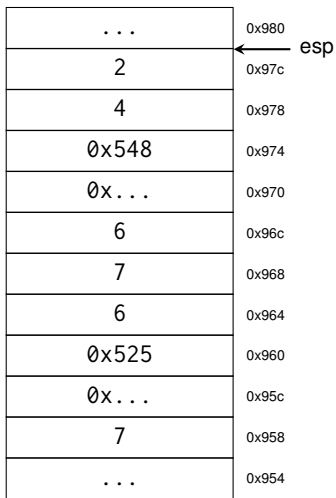
```
52a:  push ebp  
52b:  mov  ebp,esp  
52d:  lea  ...  
534:  or   ...  
538:  lea  ...  
53f:  push 0x2  
541:  push 0x4  
→ 543:  call 4fd <f>  
548:  add  esp,0x8  
54b:  leave  
54c:  ret
```



Beispiel: Programmstapel

```
→ int main(void) {  
    return f(4, 2);  
}
```

```
52a: push ebp  
52b: mov ebp, esp  
52d: lea ...  
534: or ...  
538: lea ...  
53f: push 0x2  
541: push 0x4  
543: call 4fd <f>  
548: add esp, 0x8  
→ 54b: leave  
54c: ret
```



Beispiel: Programmstapel

```
int main(void) {  
    return f(4, 2);  
}
```

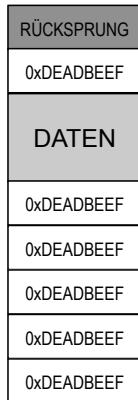
```
52a:  push ebp  
52b:  mov  ebp,esp  
52d:  lea  ...  
534:  or   ...  
538:  lea  ...  
53f:  push 0x2  
541:  push 0x4  
543:  call 4fd <f>  
548:  add  esp,0x8  
54b:  leave  
54c:  ret
```

...	0x980
2	0x97c
4	0x978
0x548	0x974
0x...	0x970
6	0x96c
7	0x968
6	0x964
0x525	0x960
0x...	0x95c
7	0x958
...	0x954

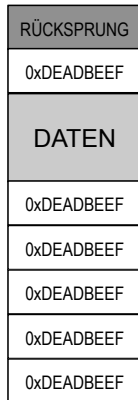
Wachstumsrichtung



- **Messung zur Laufzeit:** Wasserstandsmessung
- Grundidee: Einfügen von **Stack Canaries**
- Explizite Verwaltung des Stapelspeichers notwendig
- pthread-Bibliothek ermöglicht Verwaltung
- Mögliche Canaries
 - Lesbare Bitmuster: 0xDEADBEEF
 - Unwahrscheinliche Bitmuster: 0b101010101010...
 - Kleinere Bitmuster \rightsquigarrow größere Auflösung



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- ⚠ Keine allgemeingültigen Aussagen
 - Liefert nur den konkreten Bedarf der Messungen
 - Vorsichtige Aussagen über Worst-Case-Verhalten
- Einsatz zur dynamischen Fehlererkennung





1. (Globalen) Stack anlegen:

```
1  static unsigned int g_data[DATA_SIZE];
```

2. Thread anlegen & starten:

```
1  pthread_t thread;  
2  pthread_attr_t attr;  
3  pthread_attr_init(&attr);  
4  pthread_attr_setstack(&attr, &g_stack, STACK_SIZE);  
5  // worker function: void *run(void *param)  
6  int status = pthread_create(&thread, &attr, run, NULL);  
7  if (status != 0) { ... // handle error
```

3. Auf Thread warten:

```
1  pthread_join(thread, &ret);
```



pthread Stack

