WoCA: Avoiding Intermittent Execution in Embedded Systems by Worst-Case Analyses with Device States

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### **Energy Harvesting**

- Solar
- Radio frequencies
- Piezo-/thermo-electric







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# **Intermittent Execution**





Time

#### **Power Outages in Energy-Harvesting Systems**

- Maintain consistency in the system through power outages
- Resume operation when sufficient energy available
- System state checkpointing in non-volatile memory
- Potentially re-execute (partial) device operations

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### **Example Taskset**





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# A Device configuration determines power demand

### **Example Taskset**





# Whole-System Perspective





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### Whole-System Perspective





A System context determines power demand



- A Problem of device states with varying power demand
- A Problem of asynchronous device use in different contexts
- A Problem of **re-execution** due to transactional operation semantics



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### Goals

- Forward-progress guarantees
- Consistency guarantees
- Efficient use of available energy

Motivation

The WoCA Approach

**Evaluation** 

Conclusion





### **Device Graph**

Device states





### **Device Graph**

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- Maximum power consumption of states





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- Maximum power consumption of states
- Transitions between states





### **Device Graph**

- Device states
- Maximum power consumption of states
- Transitions between states
- Internal device configuration
  - Output power
  - Bandwidth





- Identify device-state changes on all system paths
- Decompose system into states with constant power consumption



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# **Guarantees through Analysis**





- Convert system graph to optimization problem
- Find whole-system worst-case energy consumption of tasks
- Dimension energy storage accordingly
- Start tasks only if sufficient energy is present
- Guaranteed transactional execution semantics



### **Employed Toolchain**

- Compilation with modified Clang/LLVM
  - Input: annotated source code and device graphs
  - Output: system graph, control-flow information, executable
- Resource-bound analysis with Platin @ Hepp, KPS, 2015 @ Maroun, WCET, 2024
  - Input: system graph, control-flow information, executable
  - Output: energy-consumption bounds

# **Evaluation**

### Benchmarks

- bsort: computation only
- temp: uncomplicated device use (temperature-sensor readout)
- send: complex device use (LoRa transmission)
- send-{PL,BW,SF}: varying payload, bandwidth, spreading factor
- sca: sensing, computation, actuation
- sca-isr-{lf,hf}: sca with low- and high-frequency interrupts



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- WoCA
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- all-on: device-agnostic approach
- JIT-based: checkpoints on energy interrupt and before device use



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  - Transactional guarantees through analysis bounds



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### **Results: Starvation Freedom**





Runtime for 100 Executions (Normalized to WoCA)

#### **Experiment Observations**

- Power supply constantly on after  $6 \, \mathrm{s}$
- JIT-based only makes significant progress after supply is stable
- WoCA avoids starvation